# brookfield industries, inc. NB-2000-HD2-(Main-Sub) Swinging Door Operator 

## Description:

The (Main-Sub) meets all the basic requirements as the single swing NB-2000-HD2 counterpart.
The Main-Sub operator is intended for use on double doors with an astragal and is designed to open the Lead Door first and close it last, while the Follow Door opens last and closes first. The Lead Door and Follow Door can be setup as either the left or right hand door. The Main Operator is designated as the right hand operator, while the Sub is always the left hand. The Main Operator houses a common: CPU (Central Processing Unit), Analog/Digital Converter, Class (2) 24 VDC Power Supply, and a Terminal Strip Hookup. The Sub Operator also receives basic commands from the Main Operator. All other components such as the Motor Control, Drive Train and Rotary Position Transducer are independent to both the Main and Sub operators.

The CPU has been uniquely programmed to assure the Lead and Follow doors remain in sequence during the closing cycle if one or both doors are in the Entrapment mode. The CPU program has been modified to automatically close the doors if required. The time the doors stay open can range from 0-300 seconds. This setting is titled Hold Open Delay (HOD) on the Human Machine Interface (HMI). If you do not want the automatic closing time feature, simply type in the value 301 or higher and the automatic closing time will be disabled.

We are Authorized to Mark the NB-2000-HD2 with the ETL and CE markings from Intertek Testing Services to assure compliance with UL 325, FCC Part 15 (Emissions) and the following International Standards: EN 60335-1 and -2 (Safety), EN 61000-6-2 (Immunity) and EN 61000-6-4 (Emissions). The "listing" reports specifically refer to the heavy commercial/industrial doors associated with linear accelerator rooms.

## Rating a Door Operator:

The rating of any door operator in a particular application cannot be based solely on the weight and width of the door. Other factors such as an "out-of plum" frame, "hinge bind", hinge friction, acceleration and deceleration rates or pressure differential from one side of the door to the other, may have a substantial affect on the total operating torque it takes to move the door at ANSI speeds. For Example, a $4500 \mathrm{lb}, 60$ " wide door would be well within the weight and width limitations; however, if any of the other factors are not properly controlled, the total operating torque could exceed the rated values. In the design and testing of the NB-2000HD2 door operator, we have factored these variables into the Maximum Rated Operating Torque. This assures the customer they are getting the most dependable product at a reasonable cost.

## Maximum Rated Operating Torque $=\mathbf{6 , 0 0 0} \mathrm{lb}-\mathrm{in}$

Example of torque calculation:
$T_{\text {max }}{ }^{*}=T_{\text {friction }}+T_{\text {accelddecel }}+T_{\text {stack pressure }}$

* variables can be derived via mathematical formula or can be measured values. Torque caused by "hinge bind" or "out-of plumb" doors can drastically increase the actual torque reflected to the door operator.


## Specification:

1) Forward and reverse torque adjustment: via current limit trimpot settings on the motor control to adjustment the operating torque in order to comply with the entrapment protection requirements of UL 325 . This eliminates the need for unreliable and hard to adjust manual clutches or electromagnetic clutches that are not designed for slippage or stall applications.
2) Automatic egress: or door reversal whenever entrapment protection has been violated in either the opening or closing directions; however, door shall not reverse automatically when in the latchcheck or "creep close" mode. This feature can be adjustable for time delay and reversal force.
3) Absolute position feedback control: this assures the CPU always knows the door's position. During installation, a power interruption, or if electrical noise is encountered, the door is not required to be "homed", "reset" nor go through a "learn speed cycle" at any time.
4) Manual operation: shall be in accordance with UL 325 during a power loss.
5) Supply voltage: $115 \mathrm{VAC}+/-10 \%$ (230VAC for European service) $50 / 60$ Hertz single phase. In-Line circuit breakers supplied with motor control and PLC. Surge protection, line filters, and EMI ferrites shall be included.
6) Current Consumption: maximum 6 amperes
7) PLC/Logic Control:
a) Shall be a PLC with sufficient I/O and a CPU (Central Processing Unit) with adequate memory, response times and scanning rates in order to properly control the motion and positioning of Linear Accelerator Swing Doors.
b) Outputs commands shall be the internal type, integral with the PLC. No external limit switches shall be allowed for control of door positioning.
c) A means to interface with the PLC for adjusting preset values for the open, partial open, closed, latchcheck and backcheck positions.
d) Diagnostics and troubleshooting of the PLC shall be provided with LED and modular plug-in components.
e) The PLC shall be provided with an internal battery to store the door position presets in the CPU memory.
8) Motor: $1 / 4 \mathrm{hp}$ permanent magnet 90 volt DC motor 1750 RPM TENV
9) Motor Control: shall be a full-wave, four quadrant, regenerative, 90 VDC variable speed control with the following functions:

| FWD/REV maximum speed | FWD/REV current limit | IR compensation |
| :--- | :--- | :--- |
| FWD/REV acceleration/deceleration | $1 \%$ speed regulation | $50: 1$ speed range. |

10) Speed Control: a means of controlling independent forward and reverse speeds per ANSI 156.10 as well as controlling latchcheck and backcheck "creep" speeds. This can be accomplished externally with speed pots or internally with the PLC.
11) Drive train and linkage mechanism: shall be designed to allow manual operation of the door per UL 325 in addition to assuring each component from the motor to the door attachment point is properly "sized" in order to transfer all operating torques and forces as defined for Linear Accelerator Swing Doors. Standard linkage shall consist of a pull open design with crank arm, slider block and cam follower assembly.
12) Enclosures: U-shaped 16 gage cover with $3 / 16^{\prime \prime}$ thick end plates reinforced with angle iron. See attached drawings for Main and Sub overall dimensions. (2) $7 / 8^{\prime \prime}$ dia. penetrations for $1 / 2^{\prime \prime}$ conduit on each side or metric equivalent for European installations.
13) Materials: ASTM A569, A36, AISI 1018 cold rolled steel, grade 5 bolting or better.
14) Mounting hardware: the NB-2000-HD2 shall be mounted with (6) $3 / 8$ " grade 5 diameter bolts with compatible washers and lock washers. Hardware must also be properly tightened with adequate thread engagement.
15) Finish: all exposed metal surfaces shall be prime painted.
16) Functionality test: each NB-2000-HD2 is cycle tested in position for 24 hrs. prior to shipment. Each unit is checked for leaks and that all I/O are functioning properly.
17) Installation: see drawings attached.
18) Battery Backup (optional): Opens the door during power interruption only. A 12VDC, 1.2 Ah battery with float charger and test switch shall be assembled in a grounded and vented $6^{\prime \prime} \times 12^{\prime \prime} \times 14^{\prime \prime}$ NEMA 1 enclosure. (3) holes are provided at the top of the enclosure each for $1 / 2^{\prime \prime}$ conduit. The first shall be used for a 110 V AC line from the power source, the $2^{\text {nd }}$ for a 110VAC hookup to the door operator and the $3^{\text {rd }}$ for a 12VDC hookup to the door operator. An end of travel limit switch shall also be provided.







